

Higher dimensional sieving for the number field sieve algorithms

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Discrete logarithm problem

Definition

Finite cyclic group (G, \circ) , a in G , g a generator of G .

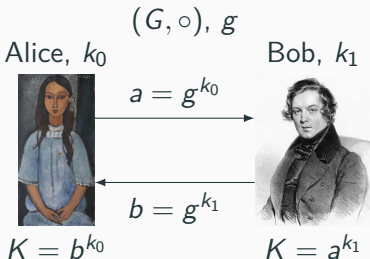
Find k in \mathbb{N} ,

$$\underbrace{g \circ g \circ \cdots \circ g}_{k \text{ times}} = a.$$

Hard to compute in $(\mathbb{F}_{p^n}^*, \cdot)$

Cryptosystems rely on:

- Diffie–Hellman KE
- DSA signature
- ElGamal encryption
- Triffie–Hellman KE



Algorithm:

1. polynomial selection
 - choose $\varphi = \gcd(f_0, f_1)$ to define $\mathbb{F}_{p^n} = \mathbb{F}_p[x]/\varphi(x)$
2. relation collection
 - find many relations $\sum_i e_i \log b_i = \sum_j e'_j \log b'_j$
3. linear algebra
 - solve linear system
4. individual logarithm
 - compute logarithm of the target

Size



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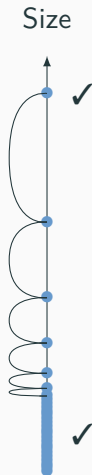
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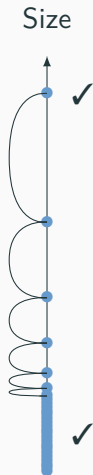
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Algorithm:

1. polynomial selection
 - choose $\varphi = \gcd(f_0, f_1)$ to define $\mathbb{F}_{p^n} = \mathbb{F}_p[x]/\varphi(x)$
2. **relation collection**
 - find many relations $\sum_i e_i \log b_i = \sum_j e'_j \log b'_j$
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L function

$$L_{p^n}(c) = \exp \left[\log(p^n)^{1/3} \log \log(p^n)^{2/3} \right] (c^{1/3} + o(1))$$

Algorithm	Type of n	Complexity	Reference
NFS	small	$c = 96/9$	[BaGaGrMo'15a]
	tiny	$c = 64/9$	[Schirokauer'92, JoLeSmVe'06,...]
exTNFS	composite	$c = 64/9$	[KiBa'16]

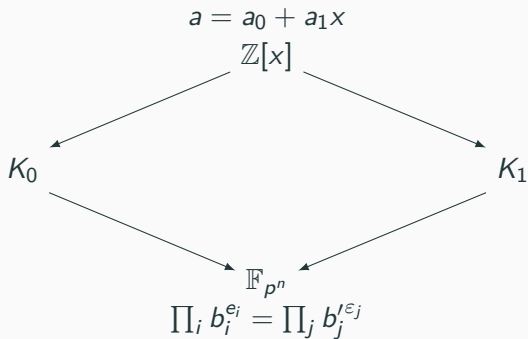
Finite field: gotta catch'em all¹

Finite field \mathbb{F}_{p^n}	Bit size	Cost: CPU days	Reference
$n = 12$	203	11	[HaAoKoTa'13]
$n = 11$	—	—	—
\vdots	\vdots	\vdots	\vdots
$n = 7$	—	—	—
$n = 6$	422	9,520	[GrGuMoTh'18]
$n = 5$	324	359	[GrGuMo'17]
$n = 4$	392	510	[BaGaGuMo'15b]
$n = 3$	593	8,400	[GaGuMo'16]
$n = 2$	595	175	[BaGaGuMo'15a]
$n = 1$	768	1,935,830	[KIDiLePrSt'17]

¹Data extracted from [DLDB]

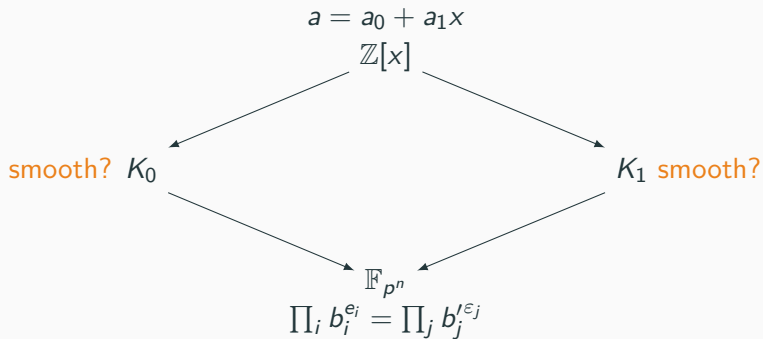
Relation collection for tiny n

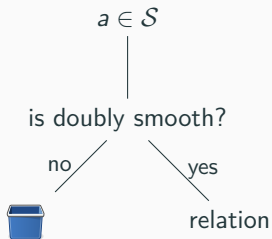
$$K_i = \mathbb{Q}[x]/f_i(x)$$



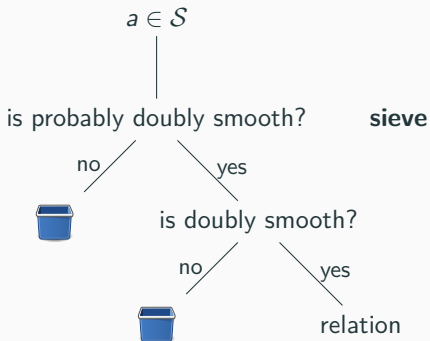
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$$K_i = \mathbb{Q}[x]/f_i(x)$$



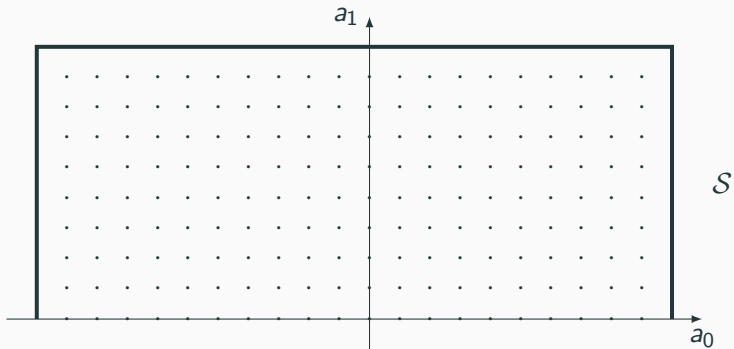


Theoretically: factorize all the possible a 's

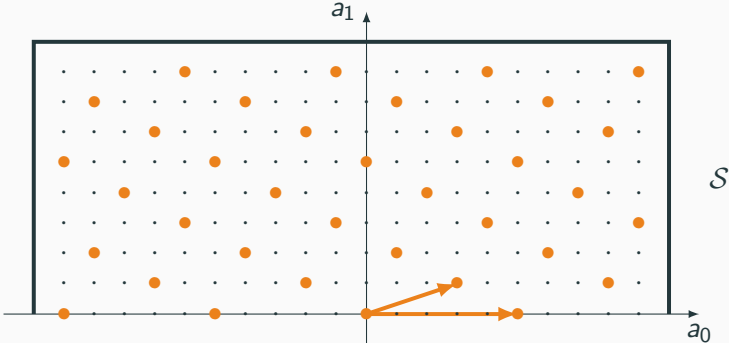


Practically: factorize only promising a 's

Sieving \equiv enumerating lattice points



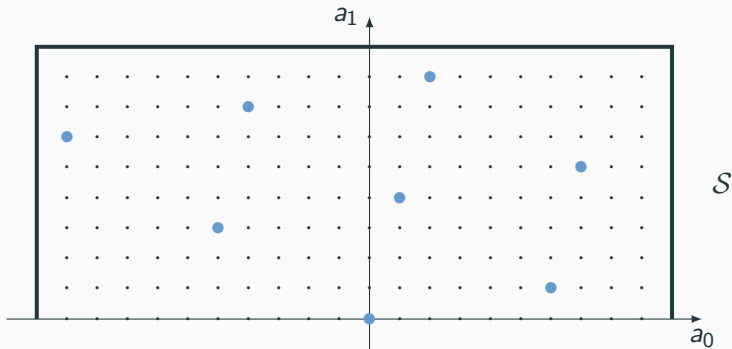
Sieving \equiv enumerating lattice points



Divisible by

\mathfrak{R}_0

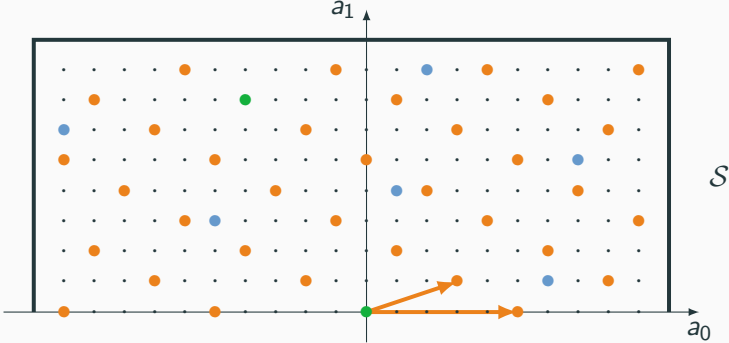
Sieving \equiv enumerating lattice points



Divisible by

\mathfrak{N}_1

Sieving \equiv enumerating lattice points



Divisible by

$$\mathfrak{K}_0, \mathfrak{K}_1, \mathfrak{K}_0 \text{ and } \mathfrak{K}_1$$

Algorithm	Type of n	# coeff. of a
NFS	small	$t \geq 2$
	tiny	2
exTNFS	$\eta\kappa$	$2\eta \geq 4$

Sieve algorithms

	Sieve algorithm	Reference
2-dim	line sieve	—
	lattice sieve	[FrKI'05]
3-dim	line sieve	[Zajac'08]
	3-dim lattice	[HaAoKoTa'15]
	plane sieve space sieve	} [GaGrVi'16]
4-dim	line sieve	—
	plane sieve	[CADO-NFS]
	sparsentv	} This work
	localntv	
globalntv		
⋮	⋮	⋮

Outline of the talk

NFS in a nutshell

Generic sieve algorithms

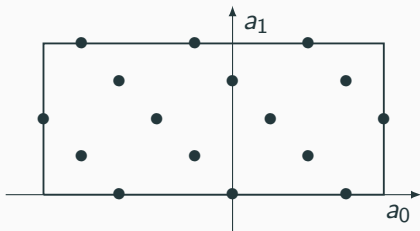
With oracle

Without oracle

Practical results

Conclusion and perspectives

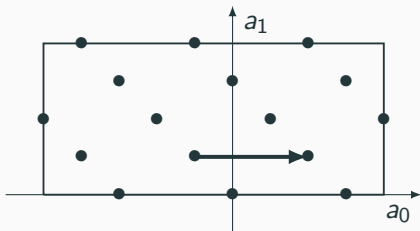
Examples in 2-dim



Using a k -transition vector

- modifies the coordinates 0 to k
- reaches an element with the smallest possible coordinate k

Examples in 2-dim

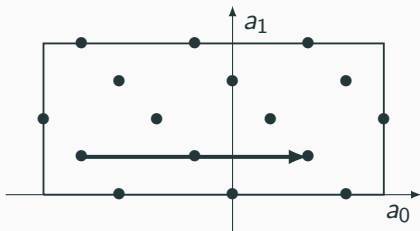


0-transition vector

Using a k -transition vector

- modifies the coordinates 0 to k
- reaches an element with the smallest possible coordinate k

Examples in 2-dim

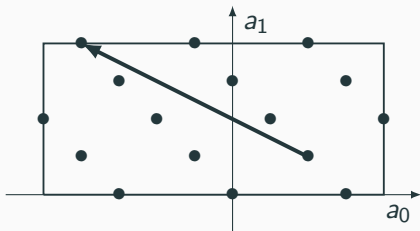


not a 0-transition vector

Using a k -transition vector

- modifies the coordinates 0 to k
- reaches an element with the smallest possible coordinate k

Examples in 2-dim

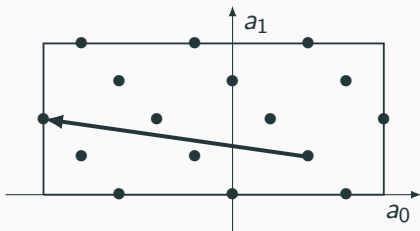


not a 1-transition vector

Using a k -transition vector

- modifies the coordinates 0 to k
- reaches an element with the smallest possible coordinate k

Examples in 2-dim

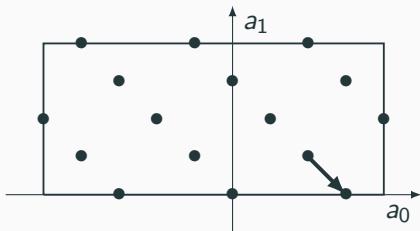


1-transition vector

Using a k -transition vector

- modifies the coordinates 0 to k
- reaches an element with the smallest possible coordinate k

Examples in 2-dim



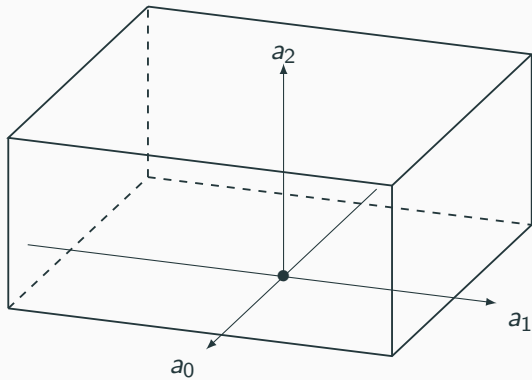
not a 1-transition vector

Using a k -transition vector

- modifies the coordinates 0 to k
- reaches an element with the smallest possible coordinate k

Generic sieve algorithms

With oracle

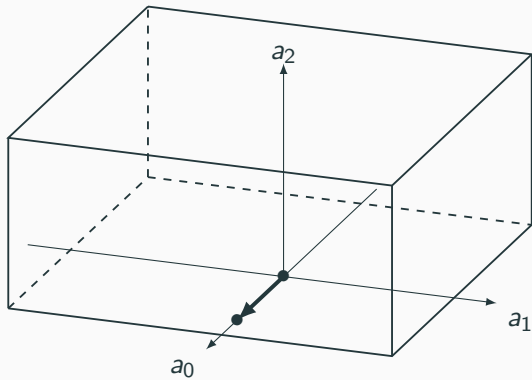


$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV

1-TV

2-TV

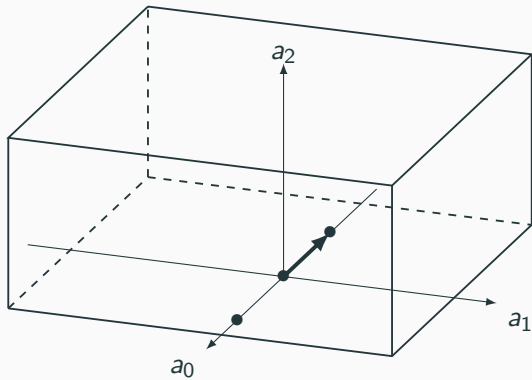


$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV
(3, 0, 0)

1-TV

2-TV

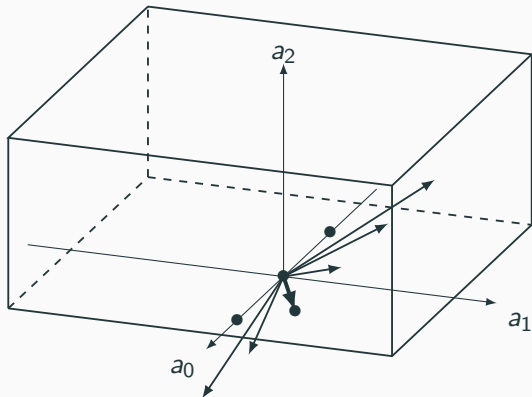


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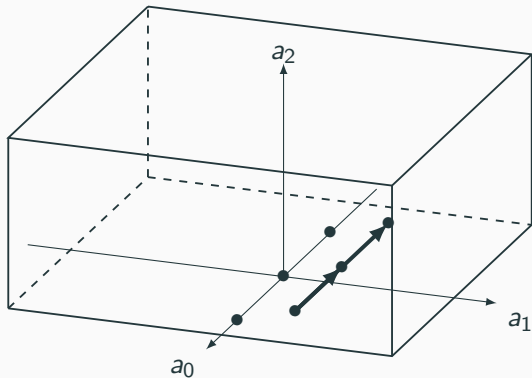
$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV
 $(3,0,0)$

1-TV
 $(8,1,0)$
 $(5,1,0)$
 $(2,1,0)$

...

2-TV



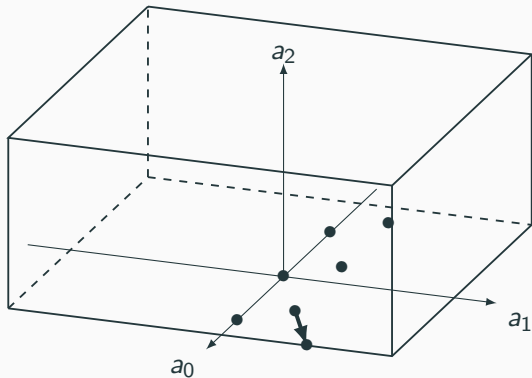
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(3, 0, 0)

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2-TV

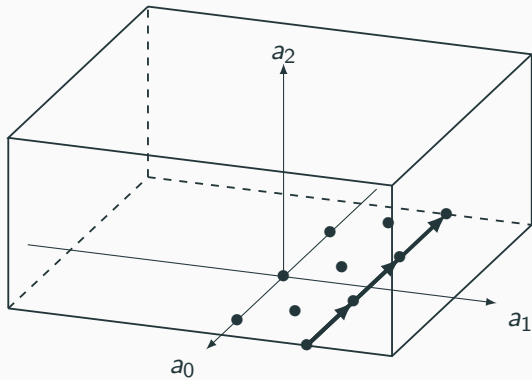


$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV
(3, 0, 0)

1-TV
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(2, 1, 0)
...

2-TV

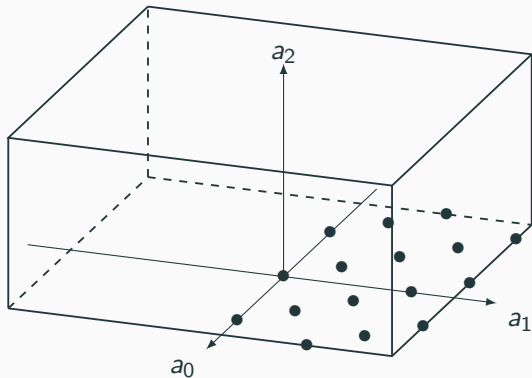


$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV
(3, 0, 0)

1-TV
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(5, 1, 0)
(2, 1, 0)
...

2-TV



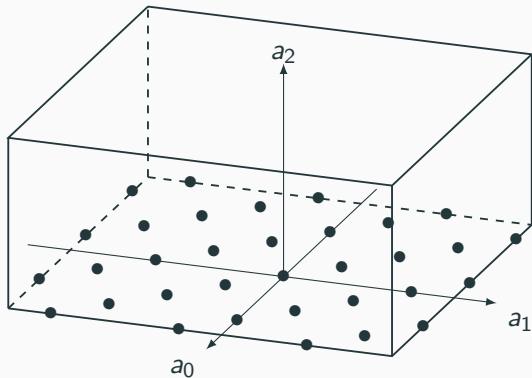
$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV
(3, 0, 0)

1-TV
(8, 1, 0)
(5, 1, 0)
(2, 1, 0)
...

2-TV

High density



$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

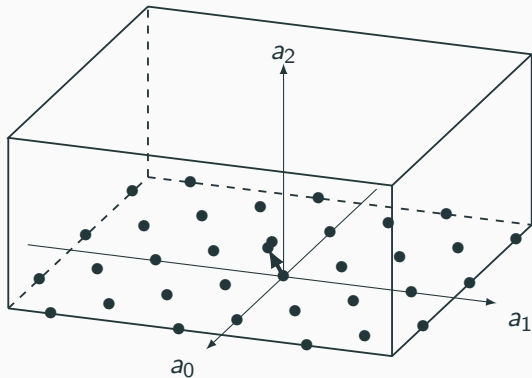
0-TV
(3, 0, 0)

1-TV
(8, 1, 0)
(5, 1, 0)
(2, 1, 0)

...

2-TV

High density



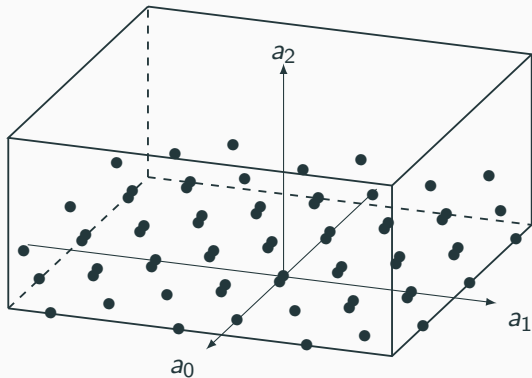
$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV
(3, 0, 0)

1-TV
(8, 1, 0)
(5, 1, 0)
(2, 1, 0)
...

2-TV
(-8, -9, 1)
(1, 0, 1)
(7, 3, 1)
...

High density



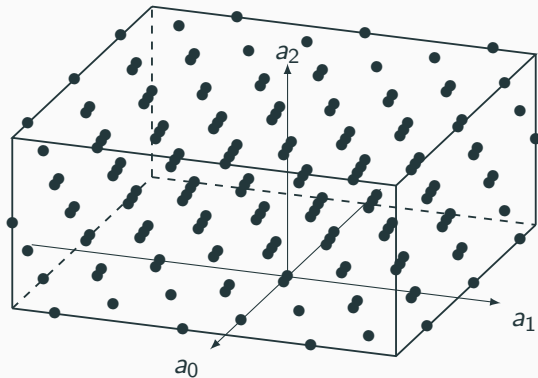
$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV
(3, 0, 0)

1-TV
(8, 1, 0)
(5, 1, 0)
(2, 1, 0)
...

2-TV
(-8, -9, 1)
(1, 0, 1)
(7, 3, 1)
...

High density



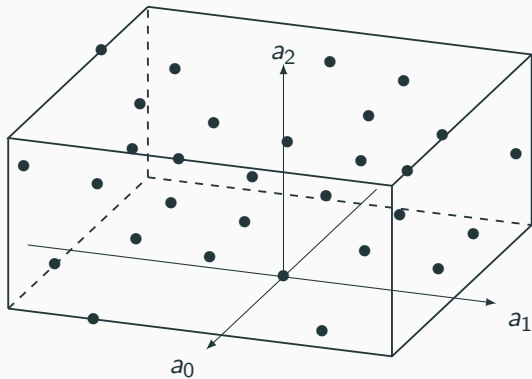
$$\begin{pmatrix} 3 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

0-TV
(3, 0, 0)

1-TV
(8, 1, 0)
(5, 1, 0)
(2, 1, 0)
...

2-TV
(-8, -9, 1)
(1, 0, 1)
(7, 3, 1)
...

Medium density



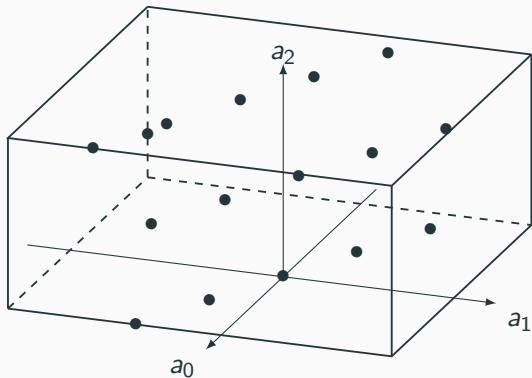
$$\begin{pmatrix} 17 & 0 & 0 \\ 10 & 1 & 0 \\ 12 & 0 & 1 \end{pmatrix}$$

0-TV
 \emptyset

1-TV
 $(-7, 1, 0)$
 $(3, 2, 0)$
 $(-4, 3, 0)$

2-TV
 $(-2, 2, 1)$
 $(-5, 0, 1)$
 $(2, -1, 1)$

...



$$\begin{pmatrix} 29 & 0 & 0 \\ 27 & 1 & 0 \\ 14 & 0 & 1 \end{pmatrix}$$

0-TV
 \emptyset

1-TV
 $(-2, 1, 0)$

2-TV
 $(-5, -5, 1)$
 $(-1, -7, 1)$
 $(-1, 0, 2)$

...

Efficient oracles do not exist

- line sieve
- plane sieve

Solution

Introduce a weaker notion than the transition-vectors

Generic sieve algorithms

Without oracle

Using a k -transition-vector

- modifies the coordinates 0 to k
- reaches an element with **the smallest possible** coordinate k

Using a k -nearly-transition-vector

- modifies the coordinates 0 to k
- reaches an element with **a different** coordinate k

Shape of the nearly-transition-vectors

Mimic the transition-vectors

- lattice of volume r
- $\mathcal{S} = \underbrace{[S_0^m, S_0^M]}_{\text{length}=l_0} \times \underbrace{[S_1^m, S_1^M]}_{\text{length}=l_1} \times \cdots \times \underbrace{[S_{t-1}^m, S_{t-1}^M]}_{\text{length}=l_{t-1}}$
- $\ell < t$ represents the density of the lattice in \mathcal{S}

Shape of transition-vectors in 3-dim

- high ($\ell = 0$): $(r, 1, 1)$
- medium ($\ell = 1$): $(l_0, r/l_0, 1)$
- low ($\ell = 2$): $(l_0, l_1, r/(l_0 l_1))$

Shape

$$(l_0, l_1, \dots, l_{\ell-1}, r/(l_0 \times l_1 \times \cdots \times l_{\ell-1}), 1, 1, \dots, 1)$$

Find (some) nearly-transition-vectors

Steps

1. Skew basis reduction
2. Small linear combinations

Skew-small-vectors are all the produced vectors

Patterns of the skew-small-vectors ($t = 6$ and $\ell = 2$)

k	globalntv	localntv	sparsentv
0	$(> 0, 0, 0, 0, 0, 0)$	$(> 0, 0, 0, 0, 0, 0)$	$(> 0, 0, 0, 0, 0, 0)$
1	$(\cdot, > 0, 0, 0, 0, 0)$	$(\cdot, > 0, 0, 0, 0, 0)$	$(\cdot, > 0, 0, 0, 0, 0)$
2	$(\cdot, \cdot, > 0, 0, 0, 0)$	$(\cdot, \cdot, > 0, 0, 0, 0)$	$(\cdot, \cdot, > 0, 0, 0, 0)$
3	$(\cdot, \cdot, \cdot, > 0, 0, 0)$	$(\cdot, \cdot, \cdot, 1, 0, 0)$	$(\cdot, \cdot, \cdot, 1, 0, 0)$
4	$(\cdot, \cdot, \cdot, \cdot, > 0, 0)$	$(\cdot, \cdot, \cdot, \cdot, 1, 0)$	$(\cdot, \cdot, \cdot, \cdot, 0, 1, 0)$
5	$(\cdot, \cdot, \cdot, \cdot, \cdot, > 0)$	$(\cdot, \cdot, \cdot, \cdot, \cdot, 1)$	$(\cdot, \cdot, \cdot, \cdot, 0, 0, 1)$

Sieve algorithm

Inputs: lattice Λ , $k < t$, a cuboid \mathcal{S} and TV 's

Outputs: elements in $\Lambda \cap \mathcal{S}$

0. set \mathbf{a} to $\mathbf{0}$
1. while $\mathbf{a}[k] < S_k^M$
 - 1.1 report \mathbf{a}
 - 1.2 if $k > 0$, call recursively the procedure with \mathbf{a} and $k - 1$
 - 1.3 add \mathbf{v} to \mathbf{a} , \mathbf{v} a k - TV and $(\mathbf{a} + \mathbf{v})[k]$ the smallest possible
2. recover initial \mathbf{a}
3. while $\mathbf{a}[k] \geq S_k^m$
 - 3.1 report \mathbf{a}
 - 3.2 as 1.2 and 1.3 with $\mathbf{a} - \mathbf{v}$

Sieve algorithm

Inputs: lattice Λ , $k < t$, a cuboid \mathcal{S} , tv 's and ssv 's

Outputs: elements in $\Lambda \cap \mathcal{S}$

0. set \mathbf{a} to $\mathbf{0}$
1. while $\mathbf{a}[k] < S_k^M$
 - 1.1 report \mathbf{a}
 - 1.2 if $k > 0$, call recursively the procedure with \mathbf{a} and $k - 1$
 - 1.3 add \mathbf{v} to \mathbf{a} , \mathbf{v} a k - tv and $(\mathbf{a} + \mathbf{v})[k]$ the smallest possible
 - 1.4 if no $\mathbf{a} + \mathbf{v}$ in \mathcal{S} , find new \mathbf{a} using k -skew-small-vector
2. recover initial \mathbf{a}
3. while $\mathbf{a}[k] \geq S_k^m$
 - 3.1 report \mathbf{a}
 - 3.2 as 1.2, 1.3 and 1.4 with $\mathbf{a} - \mathbf{v}$

Algorithm (for 1.4)

1. while $\mathbf{a}[k] < S_k^M$
 - 1.1 for all k -skew-small-vectors \mathbf{v}
 - 1.1.1 look for \mathbf{e} that reduces some coefficients of $\mathbf{a} + \mathbf{v}$
 - 1.1.2 if $\mathbf{a} + \mathbf{v} - \mathbf{e}$ in S , return $\mathbf{a} + \mathbf{v} - \mathbf{e}$
 - 1.2 set \mathbf{a} to one of the vector $\mathbf{a} + \mathbf{v} - \mathbf{e}$
2. return fail

Very costly, parsimoniously used

Generic sieve algorithms

Practical results

	4-dim	6-dim
Accuracy		fair
# <i>ssv</i> 's	fair	prohibitive
# <i>fb</i> 's	fair	prohibitive

Running time in 4-dim

- Low density
 - new sieves much faster than the plane sieve
- Very low density
 - `localntv` for low density faster than `globalntv`

Conclusion and perspectives

Three new sieve algorithms

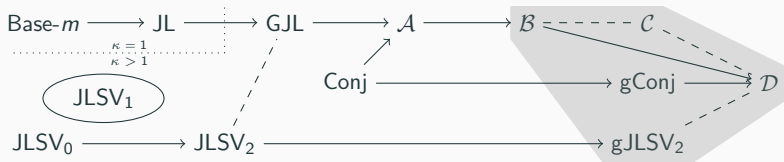
- `globalntv`, `localntv` and `sparsentv`
- implemented in `ntv.sage`, available in [CADO-NFS]

Practical results

- 4-dim reachable
- 6-dim and beyond unreachable

1. Polynomial selection
 - 11 different polynomial selection algorithms
2. Relation collection
 - 4-dim relation collection implementation?
 - cuboid search space?
3. Linear algebra
4. Individual logarithm

Polynomial selections



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